

Fig. 1

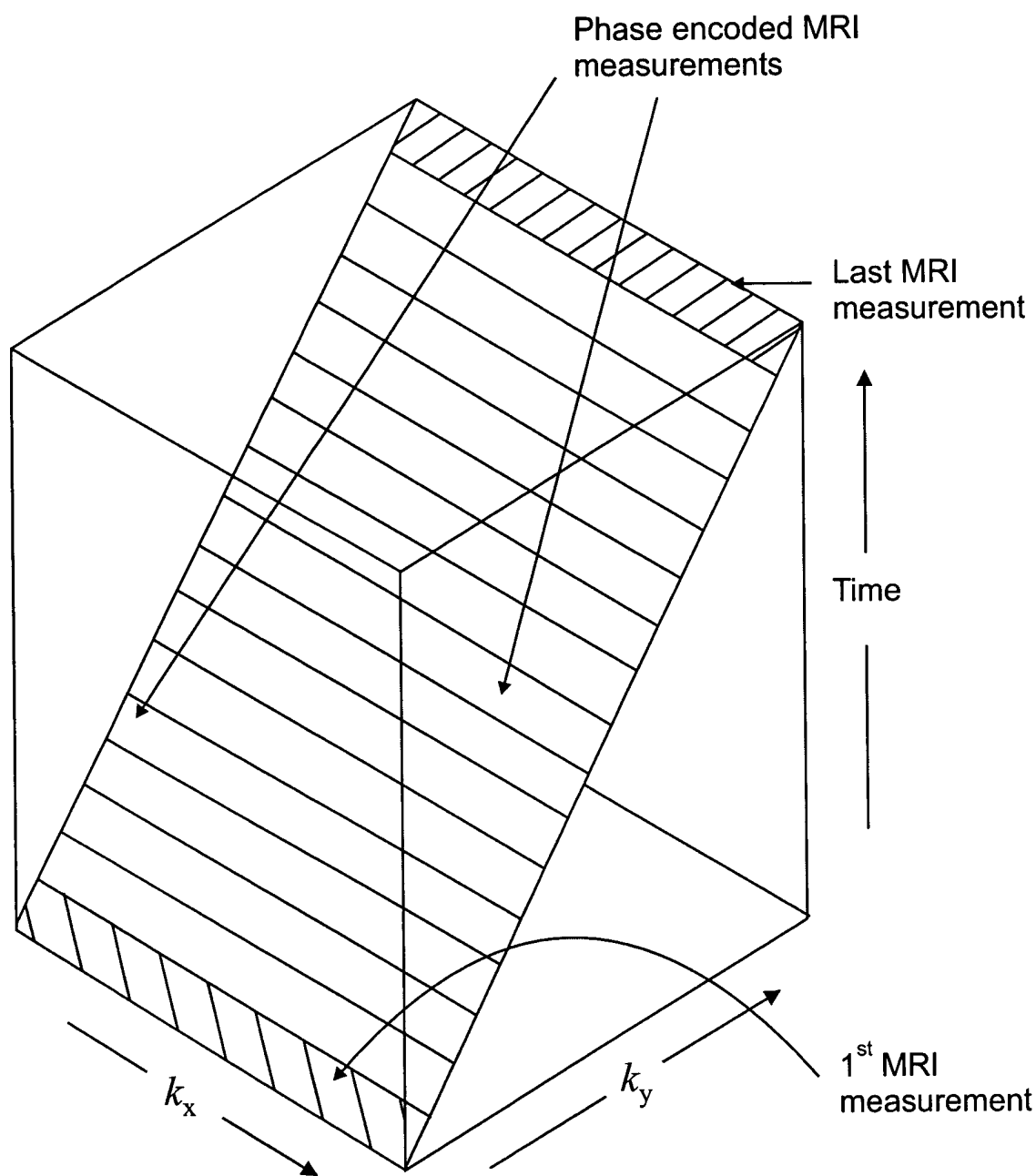


Fig. 2

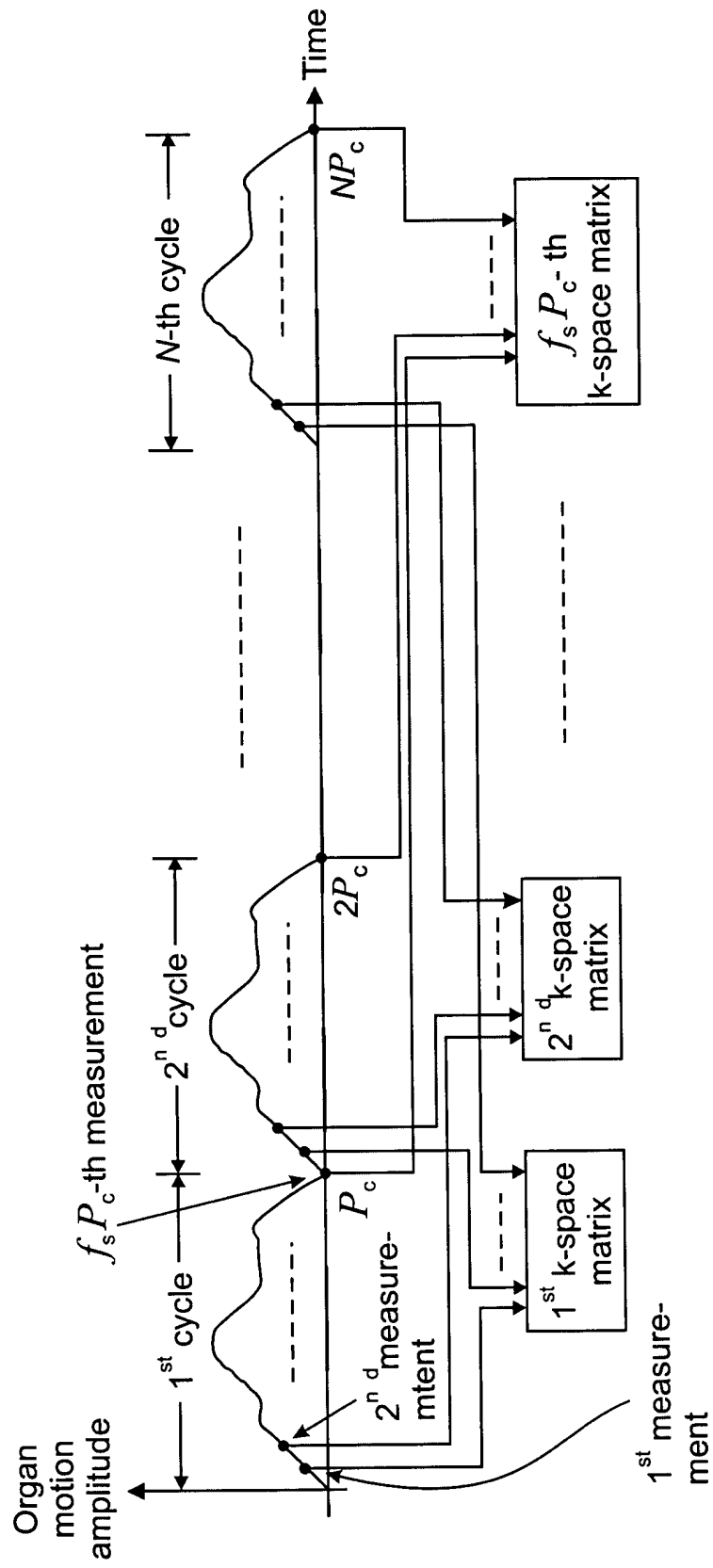


Fig. 3

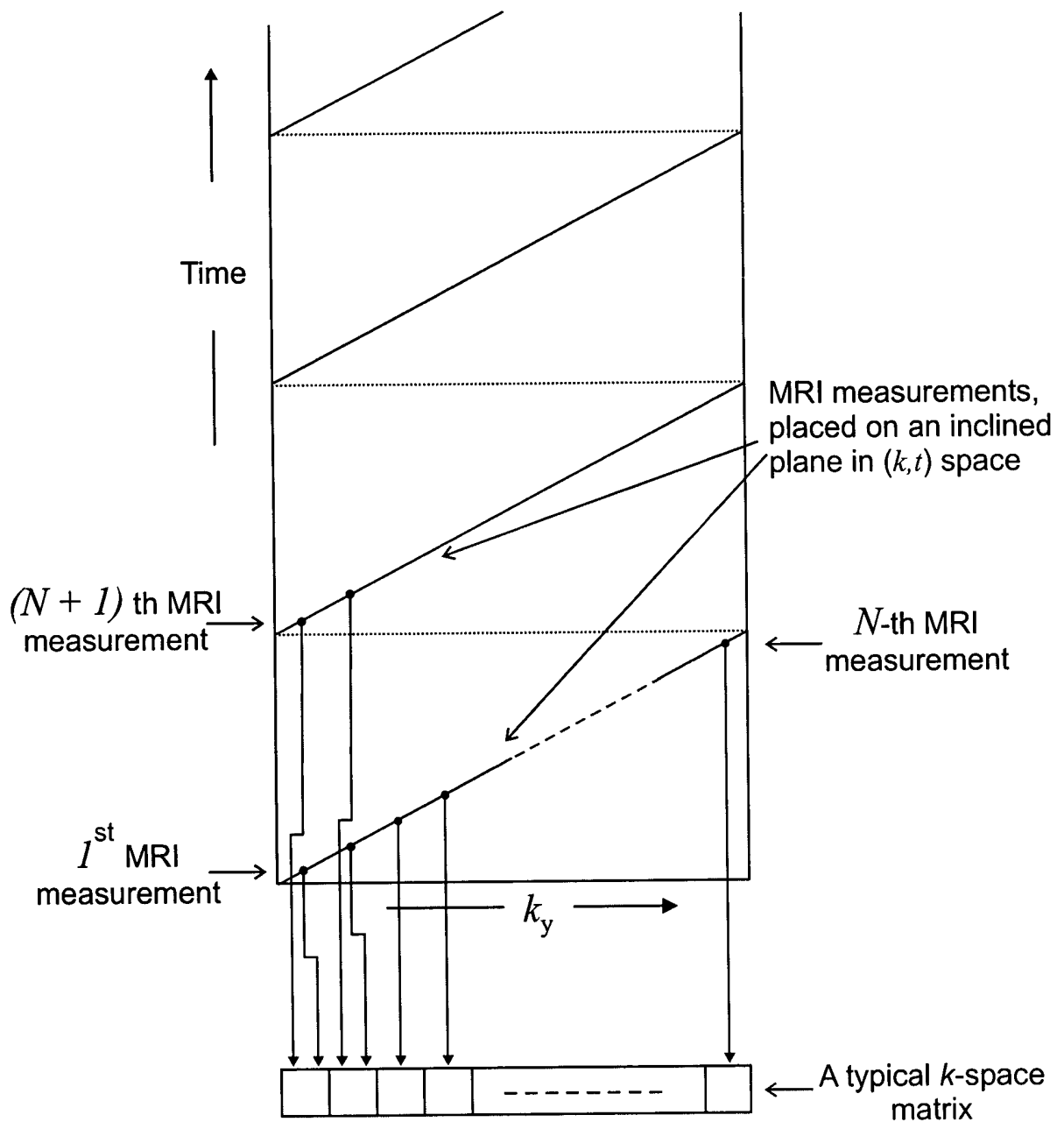


Fig. 4

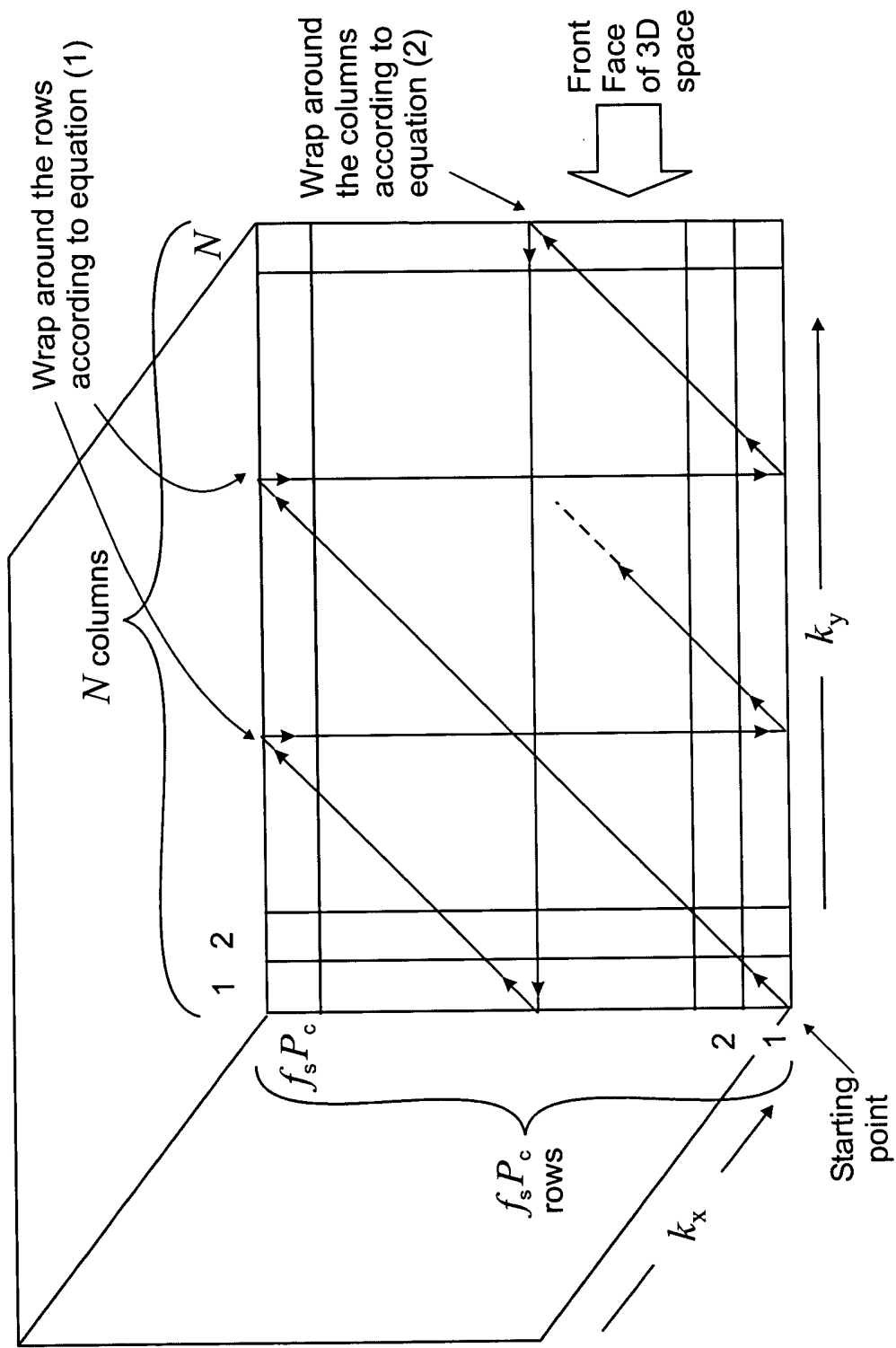


Fig. 5

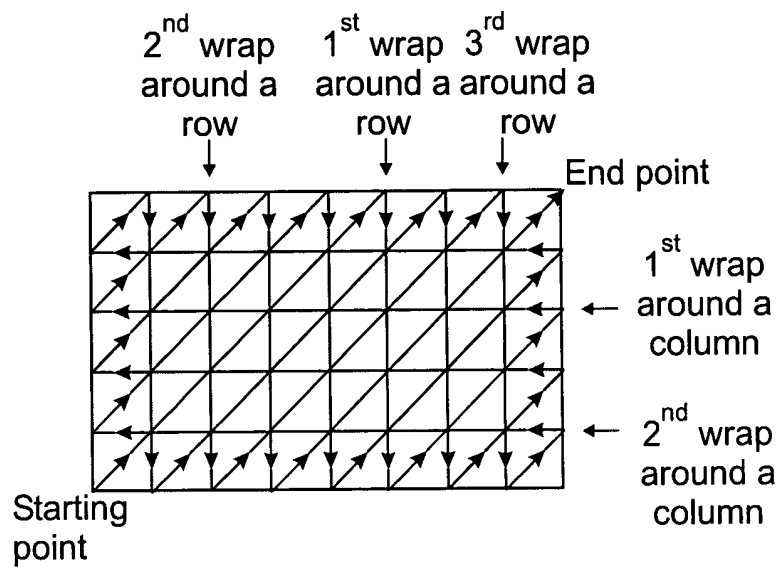


Fig 6a

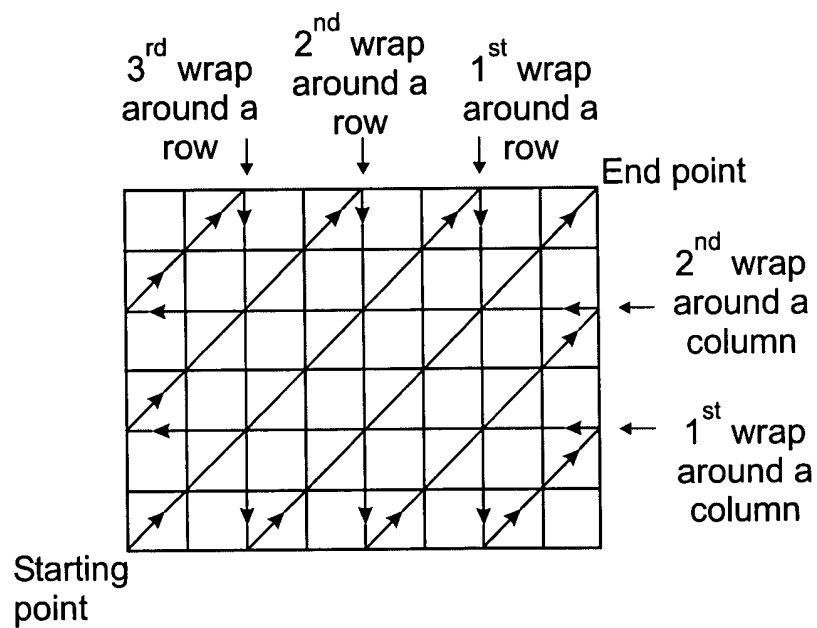


Fig 6b

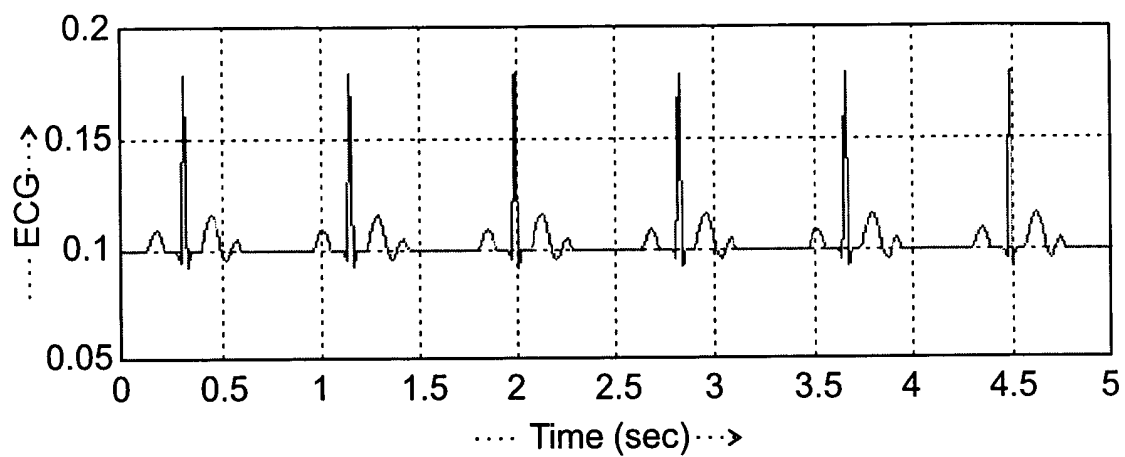


Fig. 7a

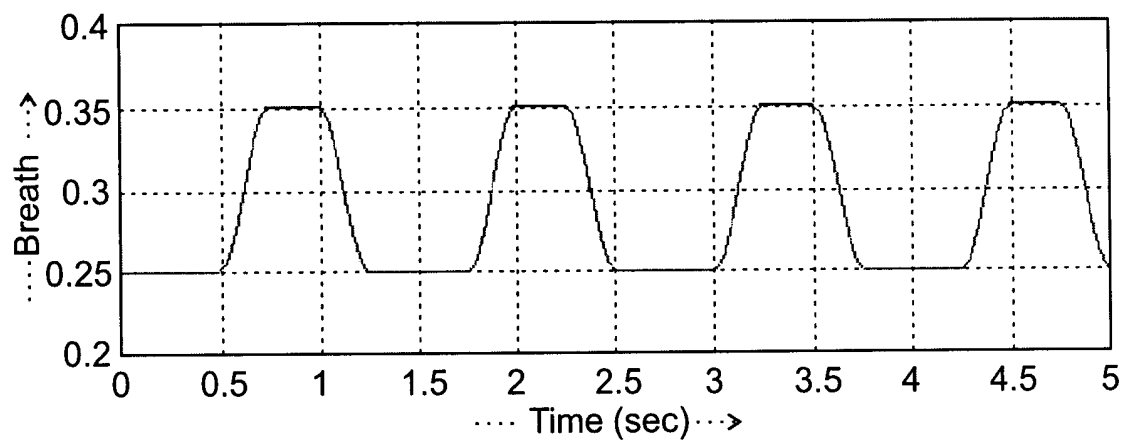


Fig. 7b

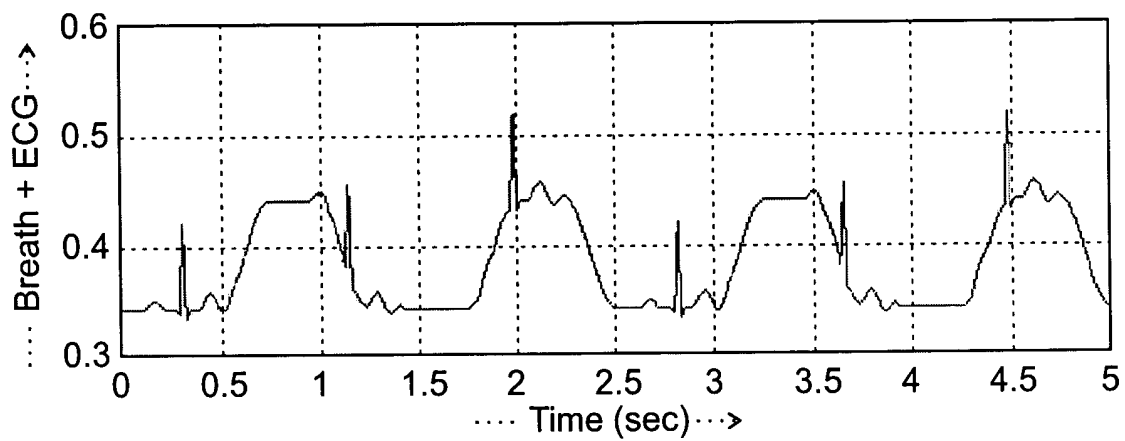


Fig. 7c

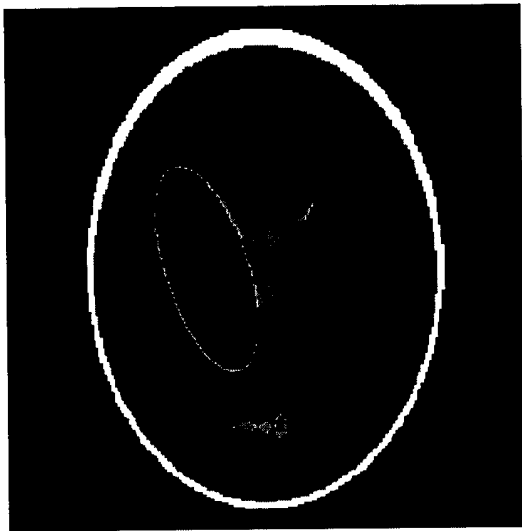


Fig. 8a

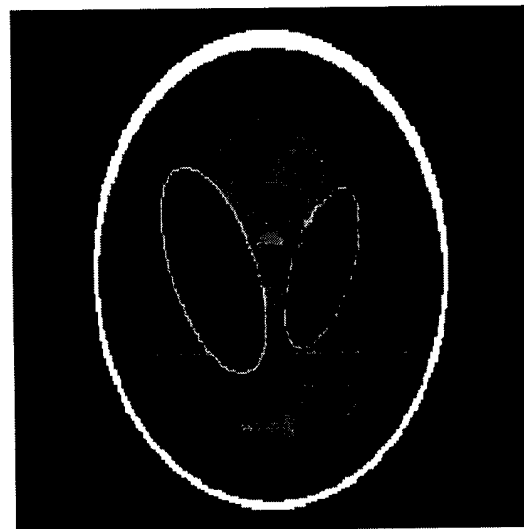


Fig. 8b

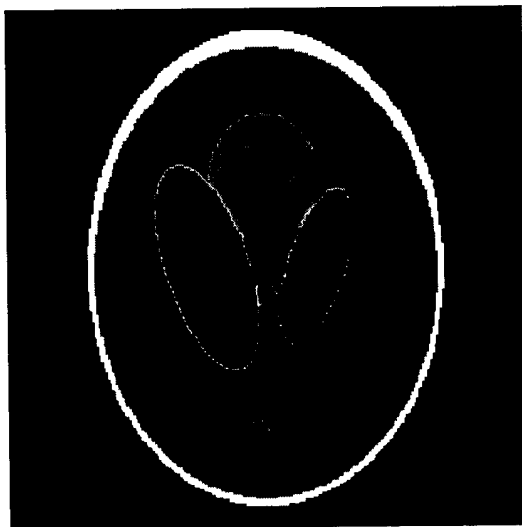


Fig. 8c



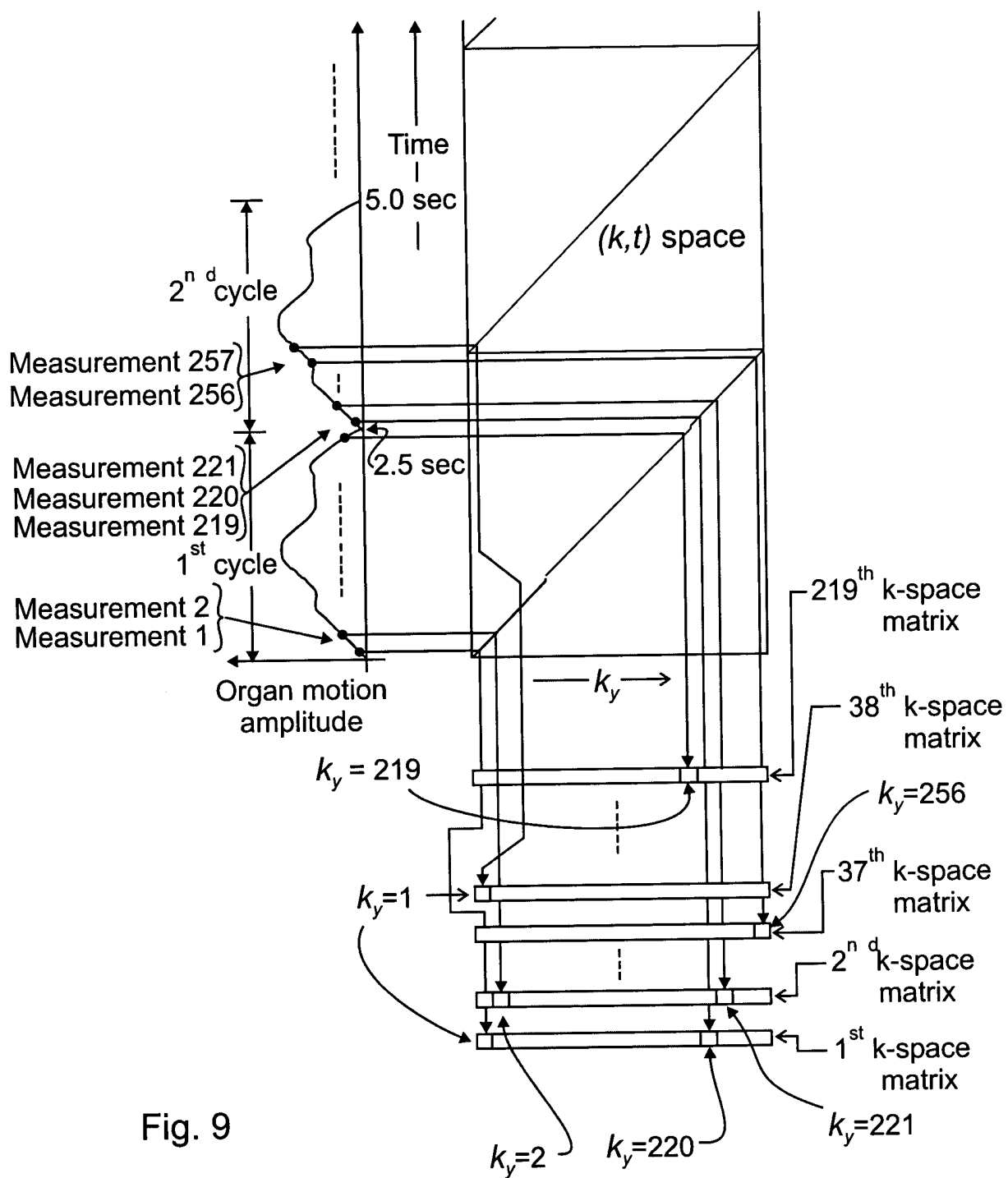


Fig. 9

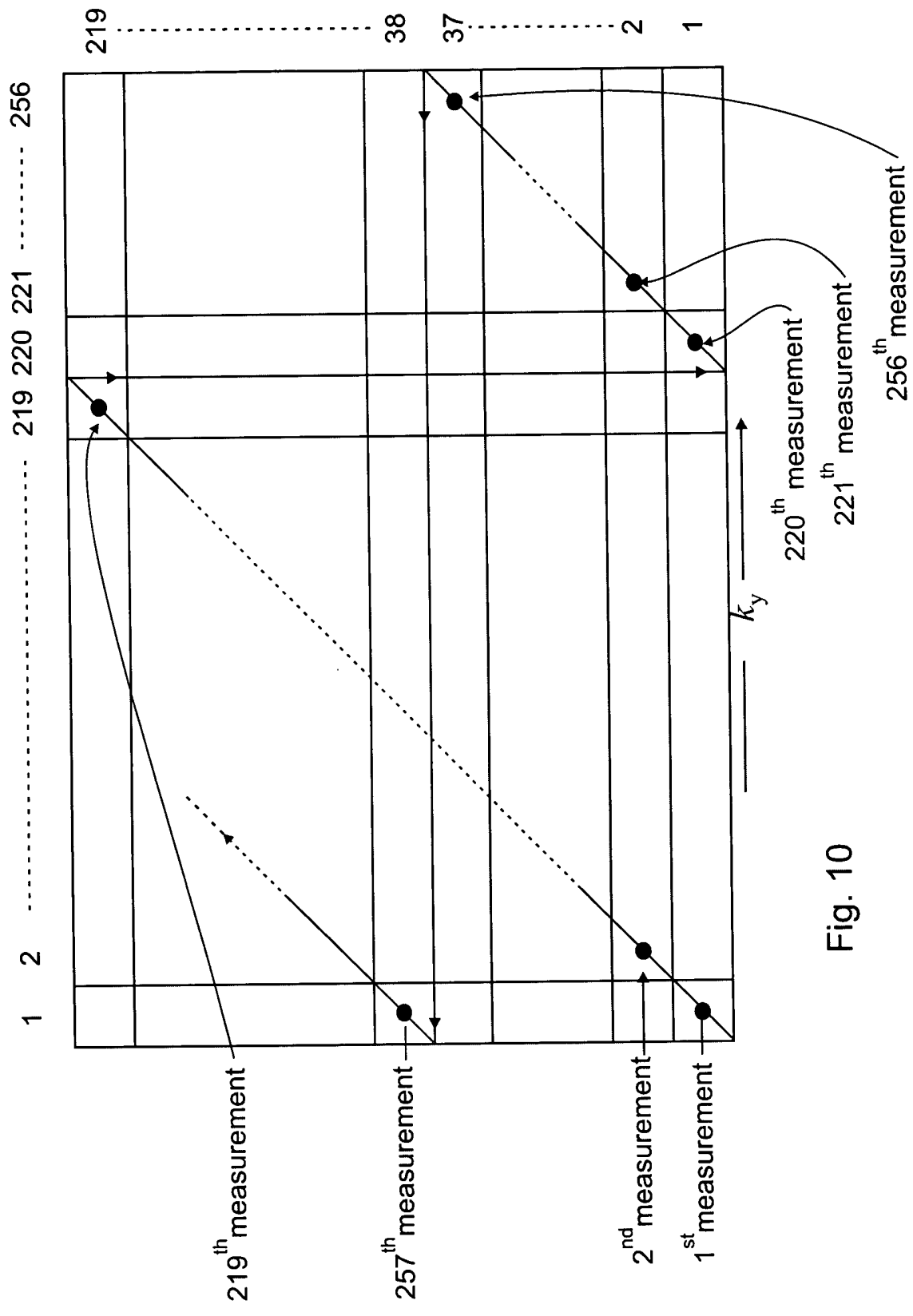


Fig. 10

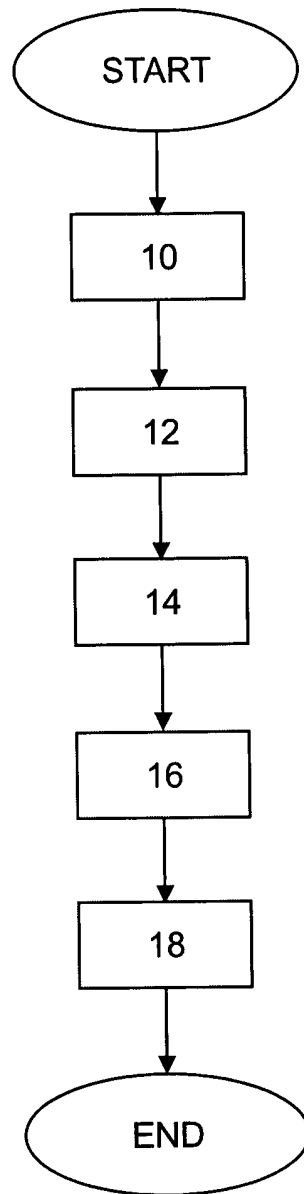


Fig. 11

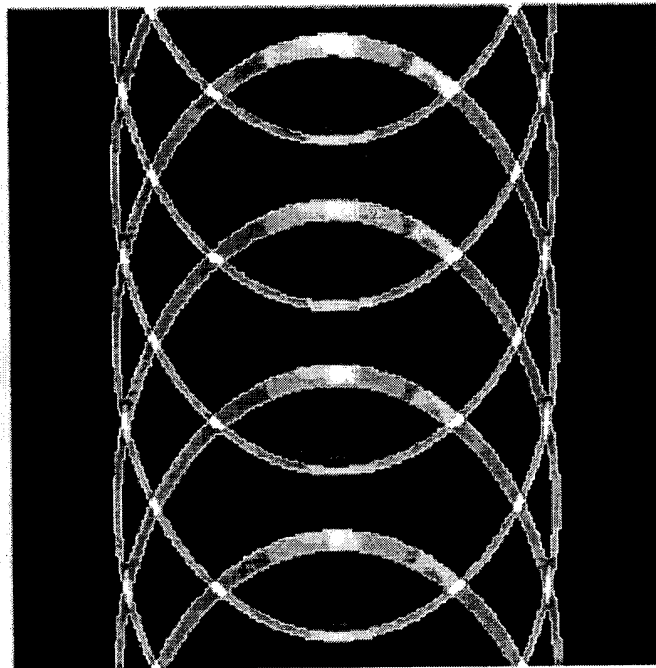


Fig. 12

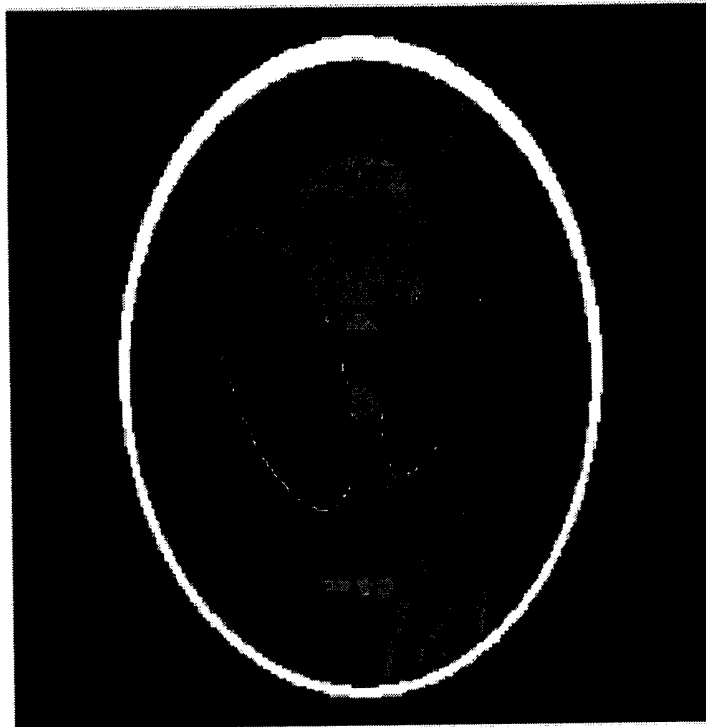


Fig. 13

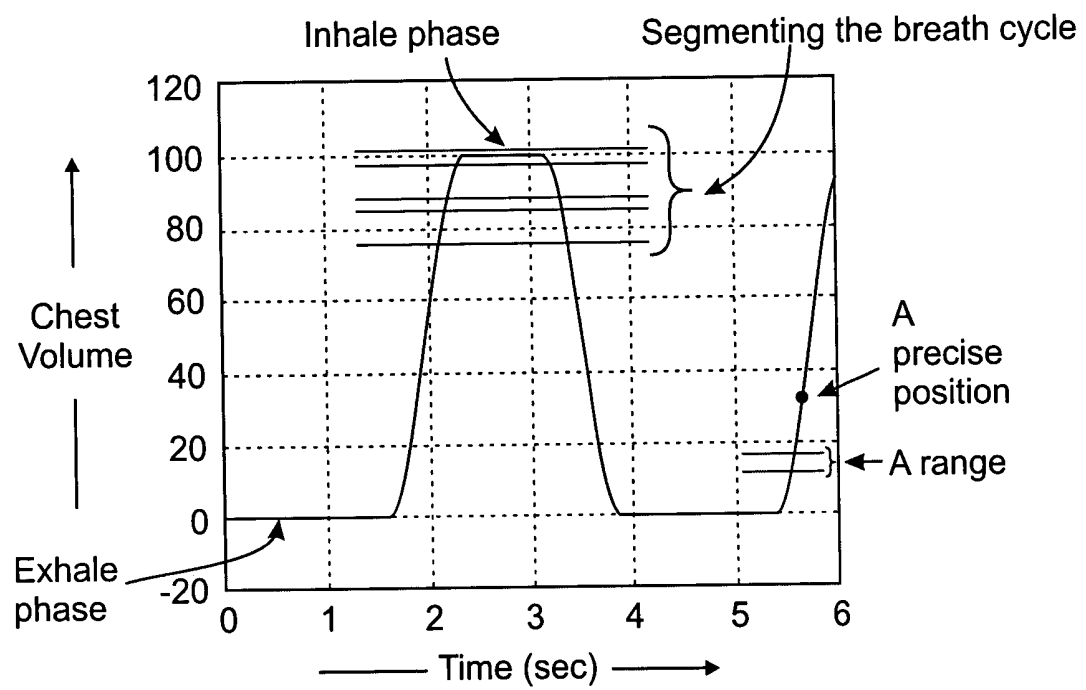


Fig. 14

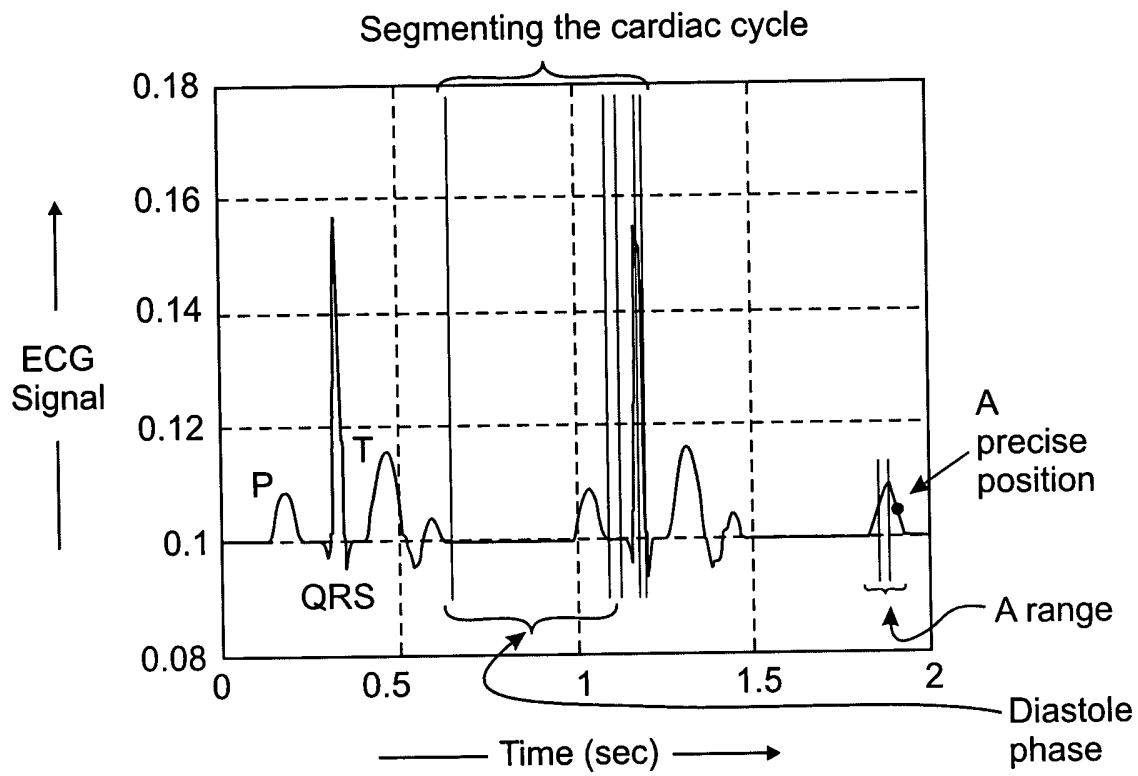


Fig. 15

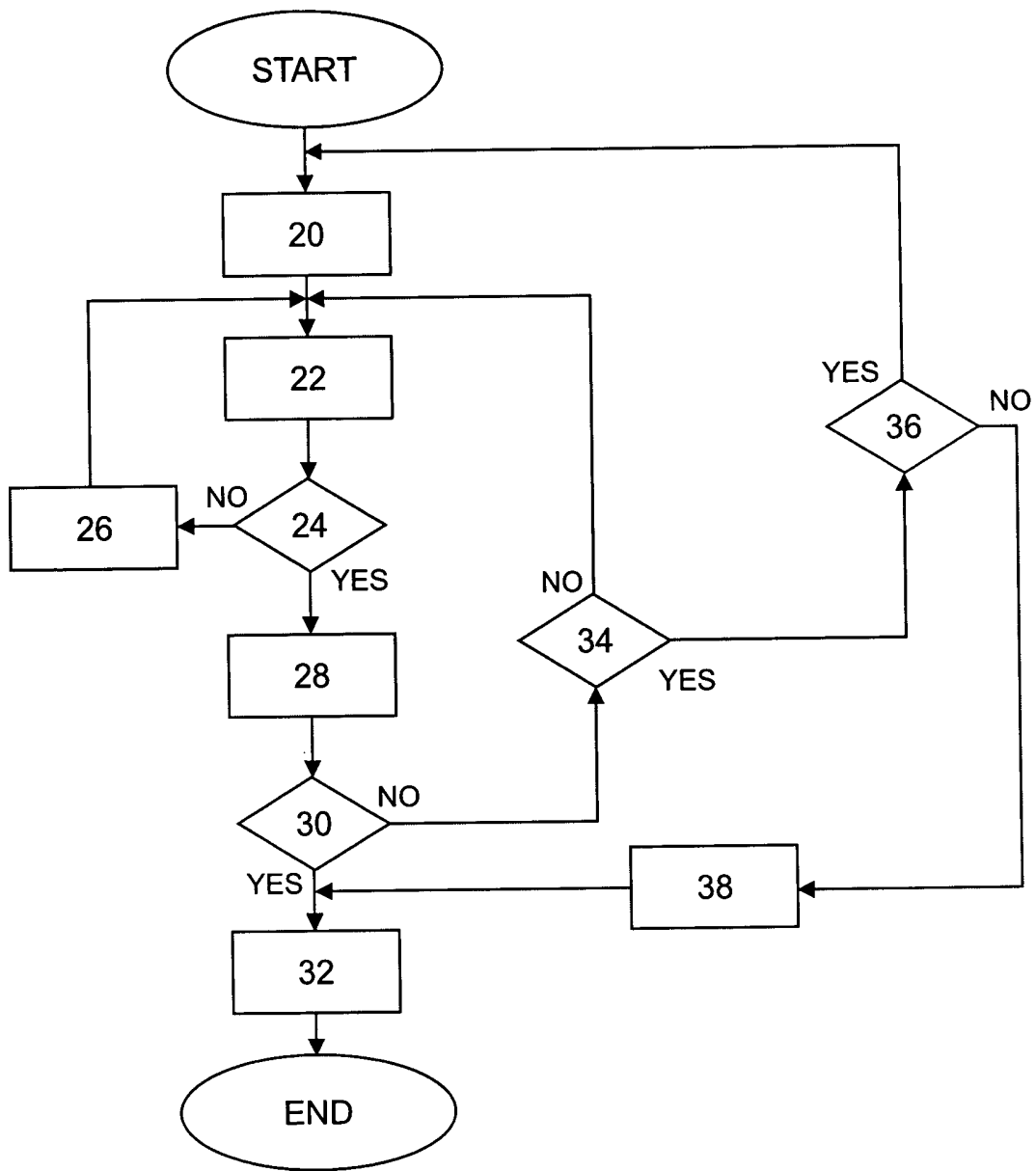


Fig. 16

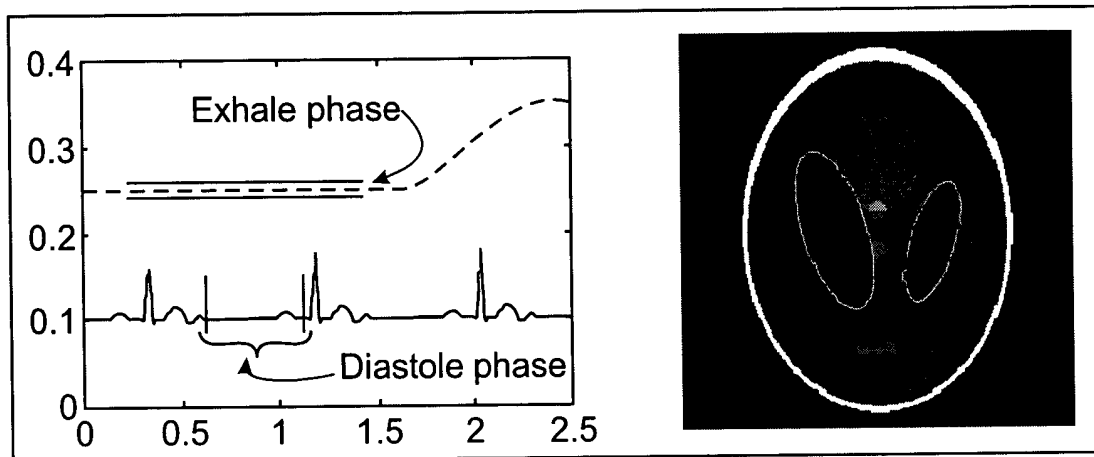


Fig. 17

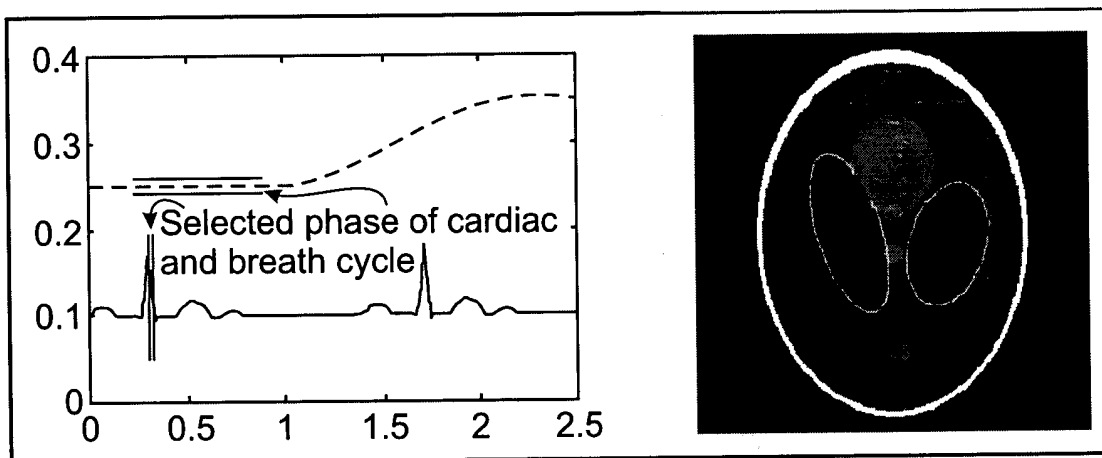


Fig. 18



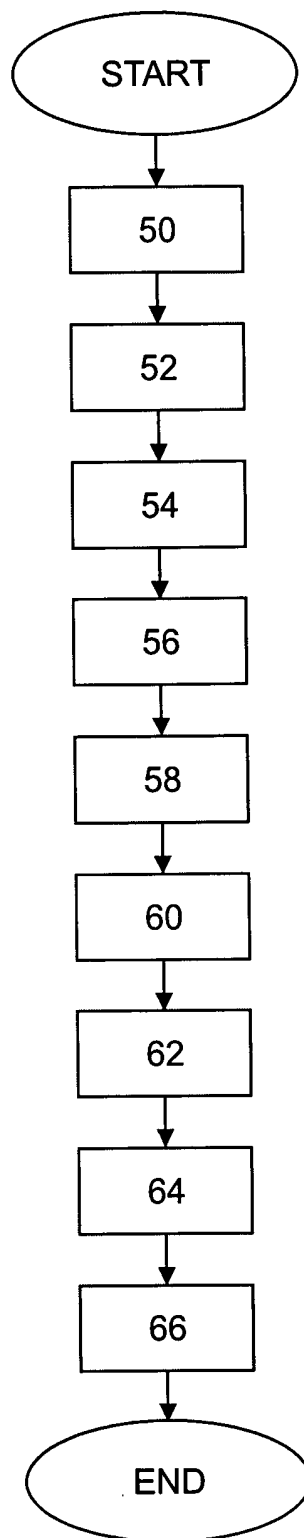


Fig. 19

(a) Initial position

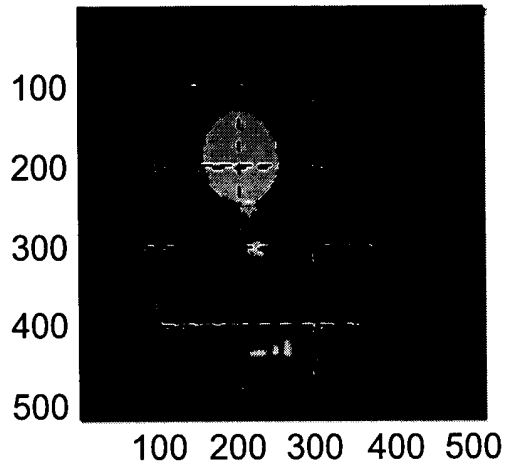


Fig. 20a

(b) Range of motion

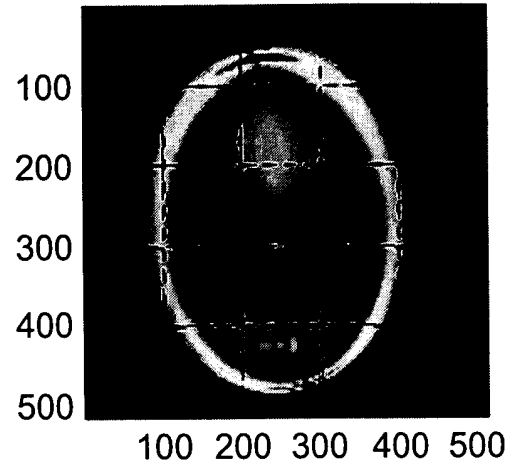


Fig. 20b

(c) Final position

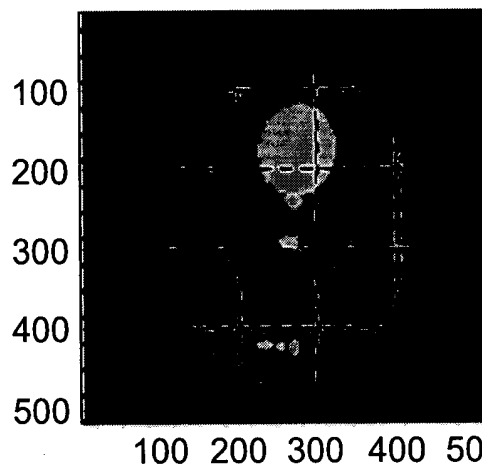


Fig. 20c

Fig. 20d

(d) Uncorrected image

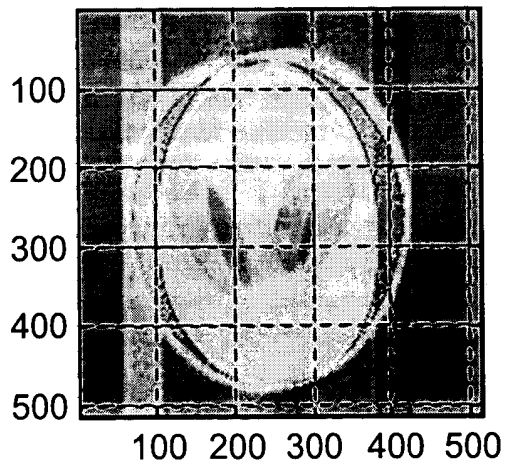
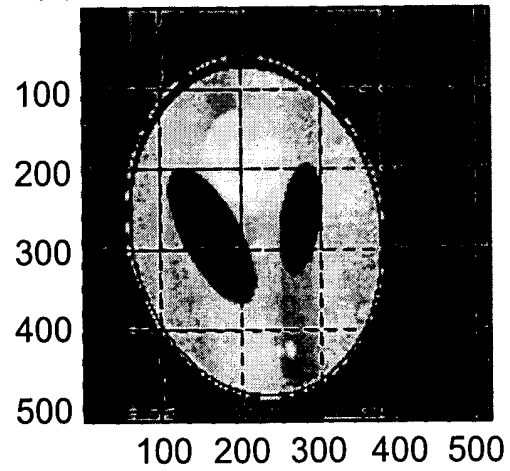


Fig. 20e

(e) Corrected w.r.t. Initial position



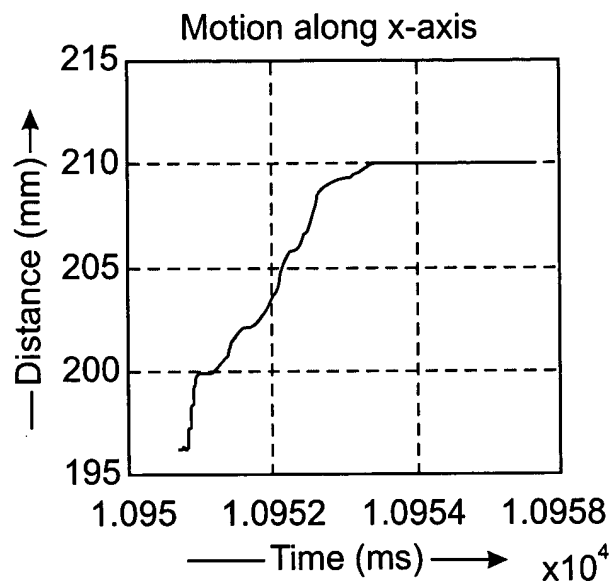


Fig. 21a

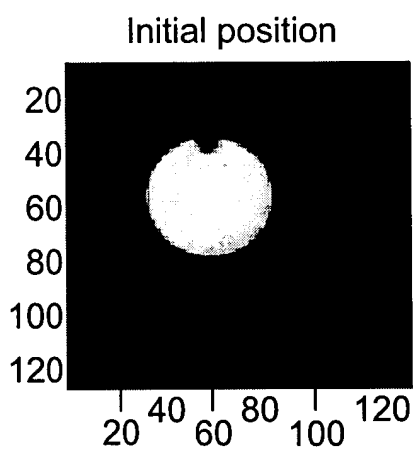


Fig. 21b

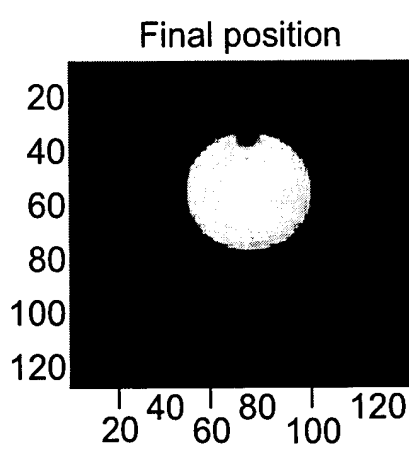


Fig. 21c

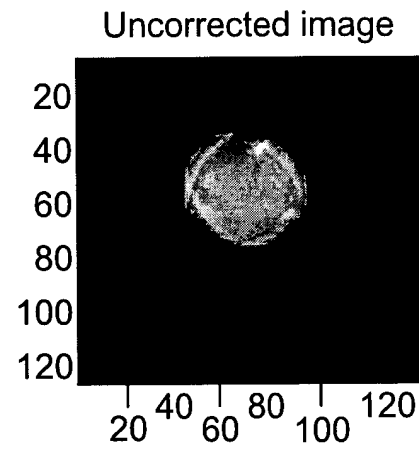


Fig. 21d

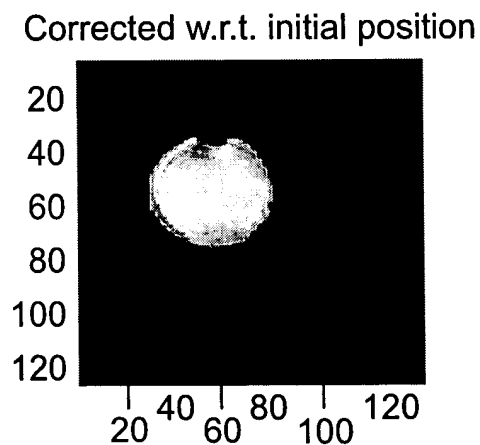


Fig. 21e

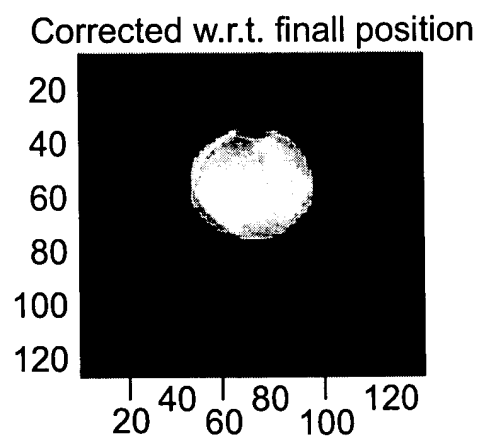


Fig. 21f

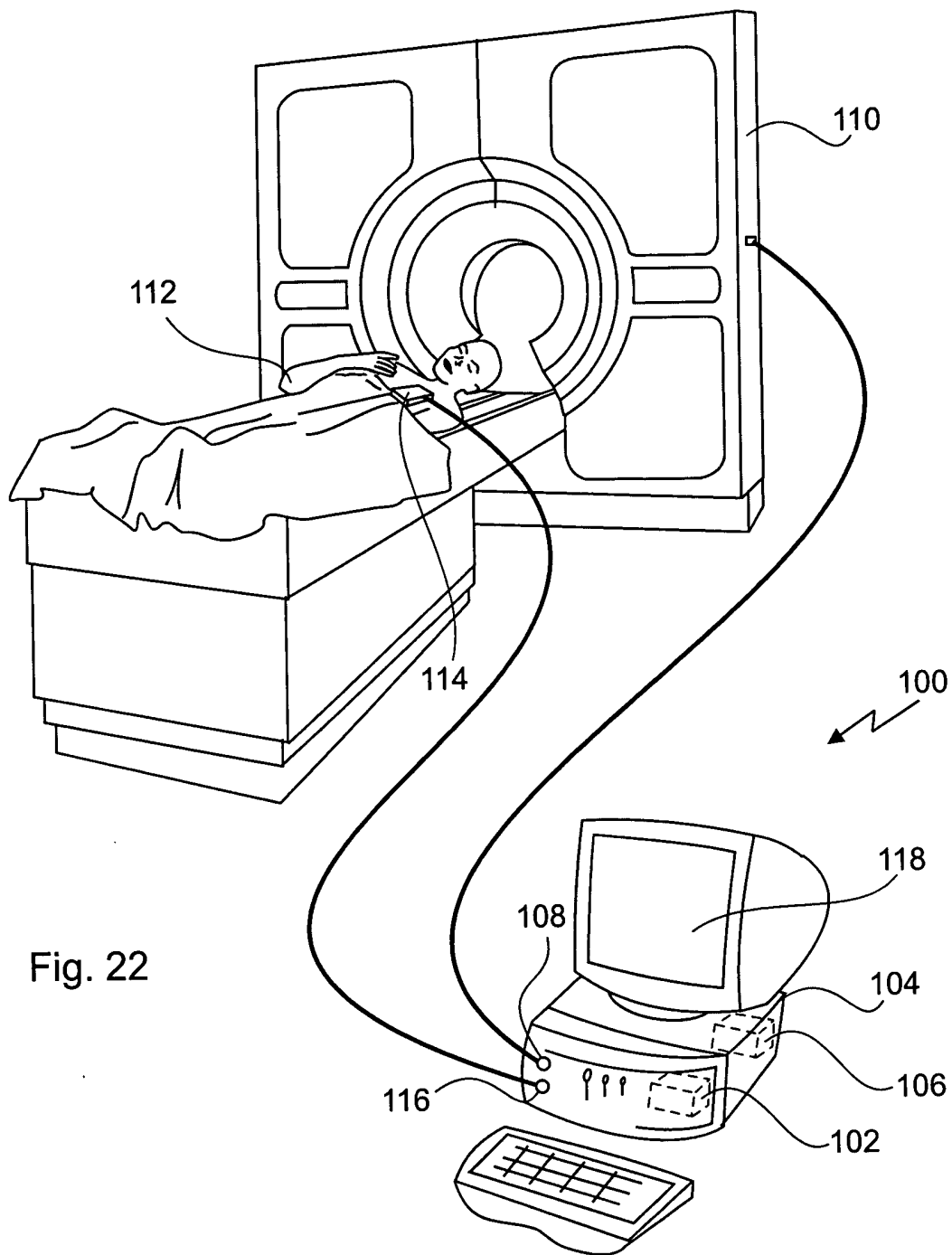


Fig. 22